

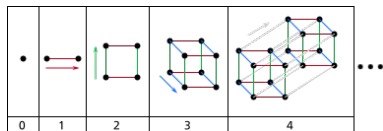
# Complicated parameter spaces and machine learning

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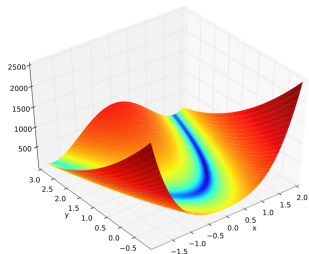
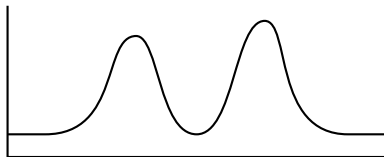
(based on: A. Hammad, M. Park, R.R., P. Saha, arXiv:2207.09959)

AI and Quantum Information Applications in Fundamental Physics  
February 15, 2023

# What makes a parameter space complicated?



- ▶ Several dimensions
- ▶ Multimodality
- ▶ Curved degeneracy
- ▶ ...



# What makes our work more complicated?

- ▶ Some high energy physics calculations (HEPC) take a **very long time/too much computational power**
  - ▶ Simulations
  - ▶ Matrix diagonalization
  - ▶ Amplitudes with many terms and corrections
- ▶ More parameters:  
**exponential increase  
in required points** × **time required  
per point**

## How we want to approach this problem

- ▶ Neural networks (NN) as generic function approximators
- ▶ Useful when training a NN could be more efficient than passing every single point through the HEPC
- ▶ Design a process where the accuracy of the NN becomes proportional to our interest in sampled regions:
  - ▶ spend, relatively, **more time sampling regions of interest**,
  - ▶ *just enough time* for low importance regions

Follow an iterative process similar to others proposed in:

Ren, Wu, Yang and Zhao [arXiv:1708.06615];

Caron, Heskens, Otten and Stienen [arXiv:1905.08628];

Goodsell and Joury [arXiv:2204.13950]

# An iterative process

0.  $L_0$ : sizable but not too large:  $(L_0, Y_0) \rightarrow$  NN-training

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1.  $L$ : large set of points:

$$L \rightarrow \text{NN-prediction} \rightarrow \hat{Y}(L)$$

2. Select an smaller set

$$(L, \hat{Y}(L)) \rightarrow \text{selection criteria} \rightarrow (K, \hat{Y}(K))$$

3. Get the correct results from the HEPC

$$K \rightarrow \text{HEPC} \rightarrow Y(K)$$

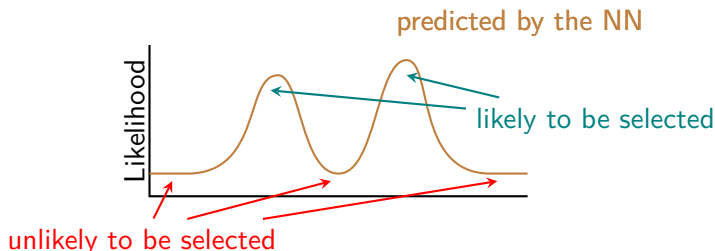
4. Train with set  $K$  and true results  $Y(K)$

$$(K, Y(K)) \rightarrow \text{NN-training}$$

## Selection of points for HEPC – Regression

We want to pass a set of meaningful points to the HEPC.

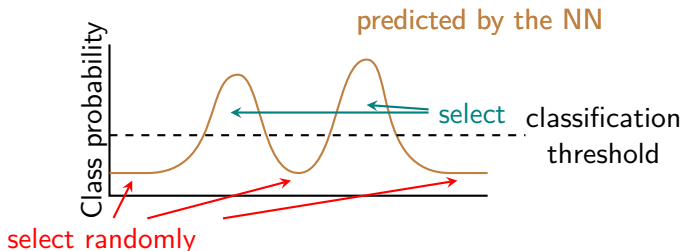
- ▶ **Highest** predicted likelihood/**lowest** predicted  $\chi^2$ 
  - ▶ But keep **diversity** of observables/likelihood
- ▶ Points predicted with low likelihood/high  $\chi^2$  may be included as part of some **rectifying strategy**.
- ▶ Fraction of random points to find new regions



## Selection of points for HEPC – Classification

We want to pass a set of meaningful points to the HEPC.

- ▶ **Highest** probability of being allowed
  - ▶ But keep **diversity** of points in and out of region of interest
- ▶ Points predicted with low probability of being allowed may be included as part of some **rectifying strategy**.
- ▶ Fraction of random points to find new regions



# Selection of points for training

Training is also time consuming

Required time depends on:

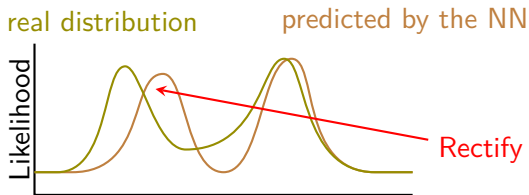
- ▶ **epochs**
- ▶ number of **hidden layers**
- ▶ number of **nodes**
- ▶ number of **points used for training**

We have to be smart about the points used for training



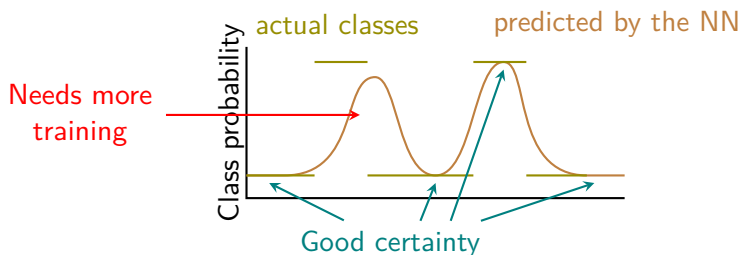
## Selection of points for training – Regression

- ▶ wrongly predicted as high likelihood: **rectify inaccurate predictions**
- ▶ What about points wrongly predicted with low likelihood/high  $\chi^2$ .
  - ▶ This needs a well thought strategy
  - ▶ There is a chance that will be corrected by additional random points.

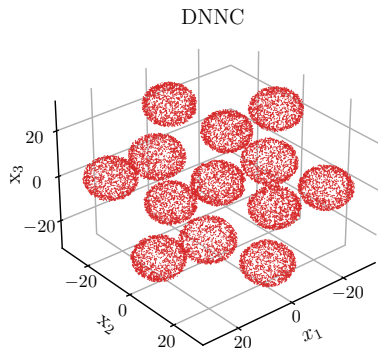
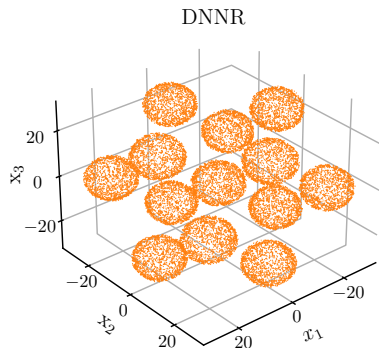


## Selection of points for training – Classification

- ▶ **True allowed:** Good certainty. These we are interested in
- ▶ **False allowed:** Confusing. These we want to correct
- ▶ **False excluded:** Confusing. These we want to correct
- ▶ *True excluded:* Good certainty. The region we care the least



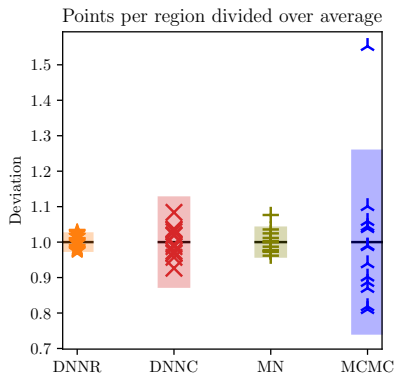
# Applied to toy model, region coverage (20k points)



$$O_{3d} = \left[ 2 + \cos\left(\frac{x_1}{7}\right) \cos\left(\frac{x_2}{7}\right) \cos\left(\frac{x_3}{7}\right) \right]^5 = 100 \pm 20$$

4 hidden layers (ReLU), 1000 epochs, Adam, loss: (MAE, Binary cross-entropy), output layer activation: (linear, sigmoid)

## Applied to toy model, deviations



Average deviation in 10 runs.  
Markers show deviation for best result.

- ▶ DNNR: regressor
- ▶ DNNR: classifier
- ▶ MN: MultiNest (pyMultiNest)
- ▶ MCMC: Markov Chain Monte Carlo (emcee)

## Boosting initial convergence

During the initial steps, predictions should be expected to be **mostly wrong**

Many options to improve initial convergence:

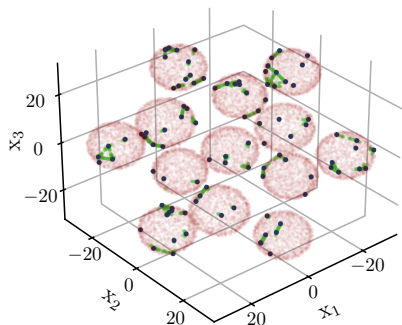
- ▶ **Naive/Brute force**: run more points to collect usable points
- ▶ Sample more points **around** known points in the target region
- ▶ Sample points **between** known points (**Synthetic Minority Oversampling Technique, SMOTE**) [Chawla et al, arXiv:1106.1813]

If these techniques work they should be needed **only in the first few iterations**.

# Boosting initial convergence

Suggest new points using 3 nearest neighbors

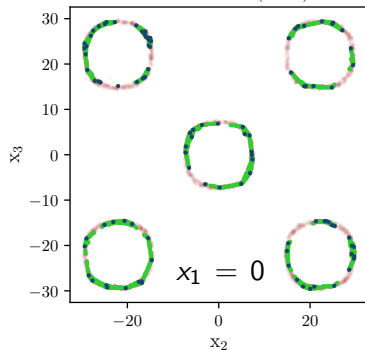
After SMOTE (4711)



efficiency:

50%

After SMOTE (4517)

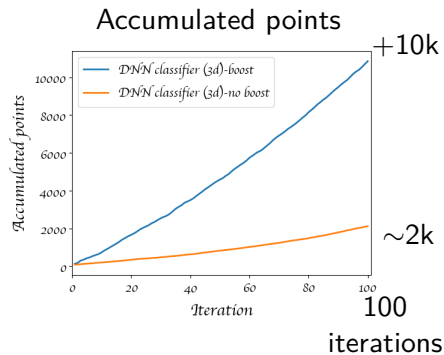
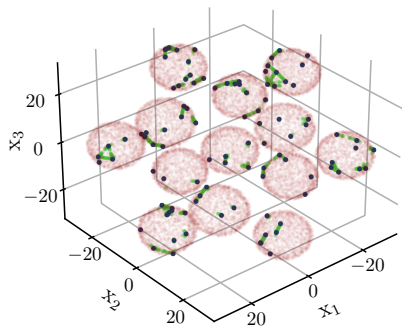


90%

# Boosting initial convergence

Suggest new points using 3 nearest neighbors

After SMOTE (4711)



## Learning the Higgs signal strength in the 2HDM

The two Higgs doublet models (2HDM) [Lee, PRD **8**, 1226] are extensions of the standard model scalar sector

$$\phi_1 = \begin{pmatrix} \eta_1^+ \\ (v_1 + h_1 + ih_3)/\sqrt{2} \end{pmatrix}, \quad \phi_2 = \begin{pmatrix} \eta_2^+ \\ (v_2 + h_2 + ih_4)/\sqrt{2} \end{pmatrix}.$$

$Z_2$  symmetry:  $(\phi_1, \phi_2) \rightarrow (\phi_1, -\phi_2) \rightarrow$  No FCNC.

Softly broken by  $m_{12}^2$  [Glashow, Weinberg, PRD **15**, 1958 (1977)]

$$\begin{aligned} V_\phi = & m_{11}^2(\phi_1^\dagger\phi_1) + m_{22}^2(\phi_2^\dagger\phi_2) - [m_{12}^2(\phi_1^\dagger\phi_2) + \text{h.c.}] + \lambda_1(\phi_1^\dagger\phi_1)^2 \\ & + \lambda_2(\phi_2^\dagger\phi_2)^2 + \lambda_3(\phi_1^\dagger\phi_1)(\phi_2^\dagger\phi_2) + \lambda_4(\phi_1^\dagger\phi_2)(\phi_2^\dagger\phi_1) \\ & + \frac{1}{2} [\lambda_5(\phi_1^\dagger\phi_2)^2 + \text{H.c.}] \end{aligned}$$

$$\tan \beta \equiv \frac{v_2}{v_1} \quad \text{with} \quad v = \sqrt{v_1^2 + v_2^2} \sim 246\text{GeV}$$



# Numerical scan

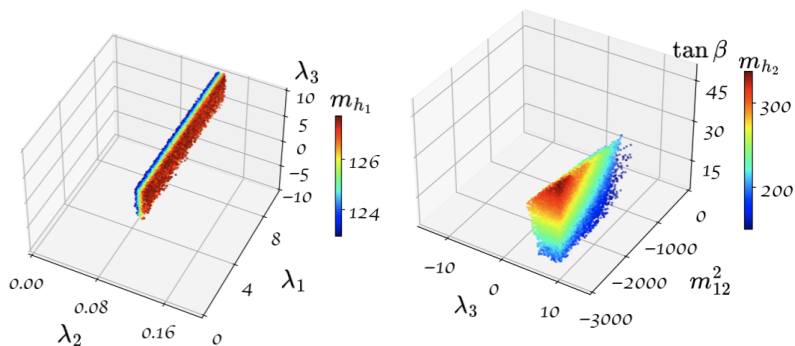
Scanned parameters and ranges

$$0 \leq \lambda_1 \leq 10, \quad 0 \leq \lambda_2 \leq 0.2, \quad -10 \leq \lambda_3 \leq 10, \quad -10 \leq \lambda_4 \leq 10, \\ -10 \leq \lambda_5 \leq 10, \quad 5 \leq \tan \beta \leq 45, \quad -3000 \leq \frac{m_{12}^2}{\text{GeV}^2} \leq 0,$$

Tools used

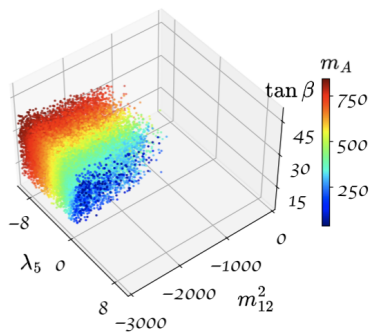
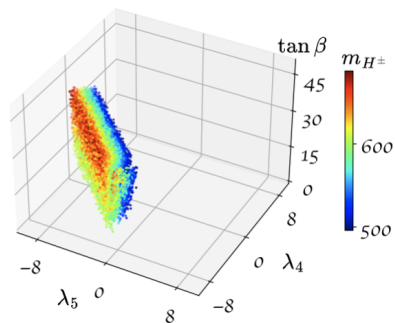
- ▶ SPheno to obtain the mass spectrum
- ▶ HiggsBounds to obtain limits on the Higgses [Bechtle et al, arXiv:1507.06706]
- ▶ HiggsSignals to obtain a  $\chi^2$  for the signals and mass of the Higgs [Bechtle et al, arXiv:1403.1582]

## Numerical scan results



4 hidden layers, 100 nodes, ReLU, 1000 epochs per iteration  
optimizer: Adam, loss: binary cross-entropy

# Numerical scan results



# What to do with this?

This process could be good for

- ▶ Adjusting complicated allowed regions
- ▶ Reduce the amount of calls to a time consuming calculation
- ▶ Compare against an ever increasing amount of experimental tests

This process could be *great* for

- ▶ A study where we already have a sense of the parameter space
  - ▶ Update limits to new data
  - ▶ Test future expectations of a model
- ▶ Anything where a precise and fast estimation of observables/likelihood could be employed (*after the model has been trained enough*)

# The code

Implementation using tensorflow

- ▶ <https://github.com/AHamamd150/MLscanner>

## Where do we want to go next?

Well known example of complicated space: phase space integration

$$p_a + p_b \rightarrow p_1 + p_2 + \dots + p_n$$

$$\int \prod_{i=1}^n d^4 p_i \delta(p_i^2 - m_i^2) \delta^4(p_a + p_b - p_1 - p_2 - \dots - p_n)$$

$3n - 4$  integration variables

Add the complexity of the squared amplitude  $|M_{a+b \rightarrow 1+2+\dots+n}|^2$

We usually look for: accurate estimation of integral, (unweighted)  
event generation, accurate simulation of background/signal

## Inspiration from previous works

- ▶ ANN as event generator.  
(Klimek, Perelstein [arXiv:1810.11509]; Chen, Klimek, Perelstein [arXiv:2009.07819])
- ▶ ML training with amplitude values.  
(Bishara, Montull [arXiv:1912.11055]; Maître, Truong [arXiv:2107.06625])
- ▶ Normalizing flows for phase space integration.  
(Gao, Höche, Isaacson, Krause, Schulz [arXiv:2001.10028])
- ▶ Normalizing flows (INN) for multichannel integration.  
(Bothmann, Janßen, Knobbe, Schmale, Schumann [arXiv:2001.05478]; Heibel, Winterhalder, Butter, Isaacson, Krause, Maltoni, Mattelaer, Plehn [arXiv:2212.06172])
- ▶ ... (and references found in the works above)

**Thanks for listening!**